Lecture 11: TMLE

Outline

- Intro to TMLE:
 - Properties
 - Implementation: TMLE for ATE estimand
- Some background on TMLE
 - Estimating Equations
 - Estimating Equations and influence curves
 - Efficient influence curve
 - TMLE solves estimating equation corresponding to efficient IC
- A-IPW: DR efficient estimating equation-based estimator
- TMLE in practice...

References

- TLB. Chapters 4-6
- Kennedy, 2017: https://arxiv.org/abs/1709.06418v1

The Roadmap

- 1. Specify **Causal Model** representing <u>real</u> background knowledge
- 2. Specify Causal Question
- 3. Specify Observed Data and link to causal model
- 4. Identify: Knowledge + data sufficient?
- Commit to an **estimand** as close to question as possible, and a **statistical model** representing real knowledge.
- 6. Estimate
- 7. Interpret Results

Estimate the Chosen Parameter of the Observed Data Distribution

- For illustration we are focusing primarily on a single statistical estimation problem
 - $O=(W,A,Y)^{\sim}P_0$
 - Statistical model is non- or semi-parametric
 - $-\Psi(P_0)=E_{W,0}(E_0(Y|A=1,W)-E_0(Y|A=1,W))$
 - If W satisfies backdoor criteria, equal to the ATE
- Focusing on three classes of estimator
 - Simple substitution (G-comp)
 - IPTW
 - Today: Double Robust- Specifically, AIPW and TMLE

Overview of Estimators

- Each class of estimator requires for its implementation an estimator of a distinct factor of the observed data distribution
- Distribution of the observed data:
- $P_0(O)=P_0(W,A,Y) = P_0(W) P_0(A|W) P_0(Y|A,W)$

Different Estimators require estimators of distinct factors of the observed data distribution

- $P_0(O)=P_0(W,A,Y)=P_0(W)P_0(A|W)P_0(Y|A,W)$
- Simple substitution estimators
 - Also referred to as "G-computation" estimators
 - Actually, rather than full $P_0(Y|A,W)$, only require estimators of $E_0(Y|A,W)$ (and $P_0(W)$)
- Consistency depends on consistent estimation of E₀ (Y|A,W)
 - Super Learning can help here, but...

IPTW Estimators

• $P_0(O)=P_0(W,A,Y)=P_0(W)P_0(A|W)P_0(Y|A,W)$

Inverse probability weighted estimators

- Consistency of IPTW estimators depends on consistent estimation of $g_0(A|W)=P_0(A|W)$
 - Super learning can help here, but....

Coming next: Double Robust Estimators

- $P_0(O)=P_0(W,A,Y)=P_0(Y|A,W) P_0(A|W) P_0(W)$ Double Robust estimators: - A-IPTW - TMLE
- These asymptotic properties typically translate into lower bias and variance in finite samples
- Can integrate machine learning and still maintain valid statistical inference
 - Meaningful CIs and p values

Coming next: Double Robust Estimators

• $P_0(O) = P_0(W,A,Y) = P_0(Y|A,W) P_0(A|W) P_0(W)$

Double Robust estimators:

- A-IPTW
- TMLE

- Implementation requires estimators of both $E_0(Y|A,W)$ and $g_0(A|W)$
- Consistent if <u>either</u> E₀ (Y|A,W) <u>or</u> g₀ (A|W) are estimated consistently

Coming next: Double Robust Estimators

• $P_0(O)=P_0(W,A,Y)=P_0(Y|A,W)P_0(A|W)P_0(W)$

Double Robust estimators:

- A-IPTW
- TMLE
- If <u>both</u> E₀ (Y|A,W) and g₀ (A|W) are estimated consistently (at rates faster than n^{-1/4}) then these estimators are efficient
 - Lowest asymptotic variance of any reasonable estimator
 - In semiparametric (or non-parametric) statistical model that makes assumptions, if any, only on P₀(A|W)

Targeted Maximum Likelihood Estimation

- TMLE is a general methodology
- As with other estimators, we will focus on estimation of the "G comp estimand" corresponding under causal assumptions to the ATE:

$$\Psi(P_0)=E_{W,0}(E_0(Y|A=1,W)-E_0(Y|A=0,W))$$

General Overview: TMLE

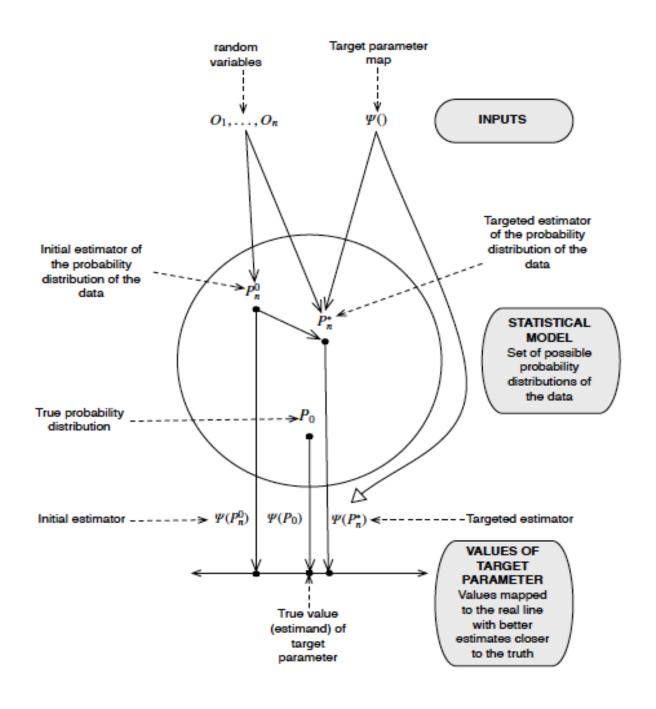
- 1. Estimate the portion of P_0 that the target parameter is a function of (i.e., estimate Q_0)
 - $-\Psi(P_0)=\Psi(Q_0)$
- What is Q₀ for the G-comp estimand?
- How could you estimate it?

General Overview: TMLE

- 2. Update initial estimator of Q_0 to obtain targeted fit of Q_0
- Targeting makes use of information in P_0 beyond Q_0 to improve estimation of ψ_0
- Provides an opportunity to
 - Reduce asymptotic bias if initial initial estimator of Q_0 not consistent
 - Reduce finite sample bias
 - Reduce variance

General Overview: TMLE

- 3. Plug in updated (targeted) estimator of Q_0 into the parameter mapping Ψ to generate estimate
- What do we call this type of estimator?
- Assume you have the targeted fit of Q_0 (we haven't talked about how to get it yet).
 - How would you estimate G comp estimand $\Psi(P_0)$?

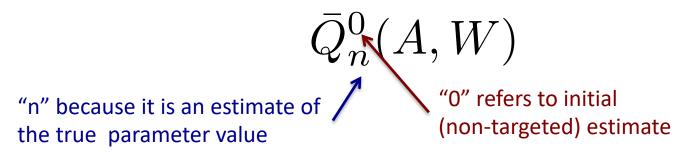


Overview of TMLE for ATE estimand

- 1. Estimate $E_0(Y|A,W)$
 - Use machine learning to respect statistical model
 - Gives "best" estimate of $E_0(Y|A,W)$
- 2. Modify this initial estimate of $E_0(Y|A,W)$
 - Target it to give better estimate of $\Psi(P_0)=E_W(E_0(Y|A=1,W)-E_0(Y|A=0,W))$
 - This targeting requires estimation of g₀(A|W)
- 3. Implement substitution estimator with new targeted estimate of $E_0(Y|A,W)$
 - For the TMLE, generally have that

$$\sqrt{n}\left(\hat{\Psi}(P_n) - \Psi(P_0)\right) \rightarrow N(0,\sigma^2)$$

- 1. Estimate $E_0(Y|A,W) \equiv \bar{Q}_0(A,W)$
 - Eg using super learner
- Notation for this initial estimate of $E_0(Y|A,W)$:



- 2. Generate predicted values for Y for each individual, given that individual's A_i,W_i
 - For participant i: $\bar{Q}_n^0(A_i,W_i)$

- 3. Estimate treatment mechanism
 - $-g_0(A|W)$
 - Eg using Super Learner

- 4. Use this estimate to create a new "clever covariate" $H_n(A,W)$ for each individual
 - For subject i

$$H_n(A_i, W_i) \equiv \left(\frac{I(A_i = 1)}{g_n(A_i = 1|W_i)} - \frac{I(A_i = 0)}{g_n(A_i = 0|W_i)}\right)$$

We will use this clever covariate to update our initial estimate

- 5. Update the initial estimate of $E_0(Y|A,W)$
- Run a logistic regression of Y_i on $H_n(A_i, W_i)$ using $\log it(\overline{Q}_n^0(A_i, W_i))$ (predicted value Y for each person) as offset (suppressing intercept term)

$$\log it(E(Y \mid A_i, W_i)) = \log it(\overline{Q}_n^0(A_i, W_i)) + \varepsilon H_n(A_i, W_i)$$

- Let ε_n denote the resulting MLE estimate of the coefficient ε on $H_n(A,W)$
- Updated estimate:

$$\overline{Q}_n^*(A, W) = \operatorname{expit}\left(\operatorname{logit}(\overline{Q}_n^0) + \varepsilon_n H_n(A, W)\right)$$

Why? Very Informal Intuition

- Want to move our initial estimate $\overline{Q}_n^0(A,W)$ closer to the truth $\overline{Q}_0(A,W) \equiv E_0(Y|A,W)$
- Why? Because our initial estimate was aimed at achieving optimal bias/variance tradeoff for full regression function $E_0(Y|A,W)$
 - Wrong bias variance tradeoff for the target parameter
 - Target parameter is lower dimensional- a single number, not a prediction for every (A,W) combination
- How? Need to do this in a targeted way
 - We want to change the initial estimate by fitting it to the data where it matters most for target parameter

Very Informal Intuition

- Not all deviations between initial estimate $\overline{Q}_n^0(A,W)$ and truth are equally important
 - With confounding, certain covariate/treatment combinations are underrepresented
 - Relative to ideal situation (from a causal perspective) in which covariate distributions are balanced across treatment levels –think of IPTW
 - A large deviation between our initial estimator and the truth for an (a,w) level for which g(a|W=w) is small is more important to our (causally motivated) target parameter than its frequency in the observed data reflects

Very Informal Intuition

- Need to make this explicit when we update
 - "Tell MLE" to give individuals with small predicted probability of observed treatment (g_n(A|W) small) more weight when updating initial fit
- How can we do this?
- One option "clever covariate"

$$H_n(A_i, W_i) \equiv \left(\frac{I(A_i = 1)}{g_n(A_i = 1|W_i)} - \frac{I(A_i = 0)}{g_n(A_i = 0|W_i)}\right)$$

 if g_n (A|W) is small, absolute covariate value is big, and thus a small change in epsilon has a bigger impact on the fit

- 6. Calculate predicted values for each individual under each treatment level of interest using the updated estimate $\overline{Q}_n^*(A,W)$
- For each individual, set a=1 and a=0 and generate predicted outcome with updated estimate

$$\overline{Q}_{n}^{*}(1,W_{i}) = \exp it(\log it(\overline{Q}_{n}^{0}(1,W_{i})) + \varepsilon_{n}H_{n}(1,W_{i}))$$

$$\overline{Q}_{n}^{*}(0,W_{i}) = \exp it(\log it(\overline{Q}_{n}^{0}(0,W_{i})) + \varepsilon_{n}H_{n}(0,W_{i}))$$
if $g_{n}(0|W_{i})$ is small,
Then $H_{n}(0,W_{i})$ is big,
and initial fit is updated more

7. Estimate $\Psi(P_0)$ as the empirical mean of the predicted values of Y for a=1 and a=0, based on the updated fit

$$\hat{\Psi}_{TMLE}(P_n) = \frac{1}{n} \sum_{i=1}^{n} \left[\bar{Q}_n^*(1, W_i) - \bar{Q}_n^*(0, W_i) \right]$$

A bit more about why this update works...

- 1. Estimating functions and estimating equations
- 2. Link to influence curves
- 3. The efficient influence curve
- TMLE is a substitution estimator that also solves the estimating equation corresponding to the efficient influence curve

Brief intro to estimating equations

- An Estimating Function $D(O|\psi)$ is a function of the observed data and the (unknown) parameter of interest
 - Observe n i.i.d. copies of O_i , i=1,...n; O^P_0
 - Parameter of interest $\Psi(P_0)=\psi$
 - Unbiased estimating function: $E_0[D(O|\psi)]=0$
- Estimating Equation: $0 = \frac{1}{n} \sum_{i=1}^{n} D(O_i | \psi)$
- Estimator: ψ_{n} defined as the solution satisfying $\frac{1}{n}\sum D(O_i|\psi_n)=0$

Simple example: Population mean

- Observe n i.i.d. copies of O_i=Y_i; O~P₀
- Parameter of interest $\Psi(P_0) = \psi = E_0(Y)$
- Let D(O | ψ)=Y- ψ
 - Note: $E_0[D(O|\psi)]=E_0(Y)-\psi=0$
- Estimating Equation: $0 = \frac{1}{n} \sum_{i=1}^{n} (Y_i \psi)$
- Estimator $\psi_n = \frac{1}{n} \sum_{i=1}^n (Y_i)$
 - Sample mean as estimator of population mean can be understood as root of an estimating equation

IPTW estimator defined as solution to an estimating equation

- Observe n i.i.d. copies of O_i=(W_i A_i Y_i); O^P0
- Parameter of interest: $\Psi(P_0) = E_0 \left(\frac{I(A=a)}{g_0(A|W)} Y \right)$
- Estimating function: $D_{IPTW}(O|g,\psi) = \frac{I(A=a)}{g(A|W)}Y \psi$
 - Note: if treatment mechanism g is not known, then it is a "nuisance parameter" which must be estimated
- Estimating Equation: $0 = \frac{1}{n} \sum_{i=1}^{n} \frac{I(A_i = a)}{g_n(A_i|W_i)} Y_i \psi$

(Non-stabilized) IPTW estimator:
$$\psi_n = \frac{1}{n} \sum_{I=1}^n \frac{I(A_i = a)}{g_n(A_i|W_i)} Y_i$$

Influence Curves and Estimating Functions

 Recall: An estimator is asymptotically linear with influence curve IC(O_i) if it satisfies

$$\psi_n - \psi = \frac{1}{n} \sum_{i=1}^n IC(O_i) + o_{P_0} \left(\frac{1}{\sqrt{n}}\right)$$

$$\mathsf{E_0}(\mathsf{IC}(\mathsf{O})) = 0$$

$$\mathsf{Var}(\mathsf{IC}(\mathsf{O})) \text{ Finite}$$

$$\mathsf{Converges to 0 in probability as n-} \mathsf{ver}(\mathsf{IC}(\mathsf{O})) \text{ Finite}$$

$$\mathsf{ver}(\mathsf{IC}(\mathsf{O})) = 0$$

- Because E₀(IC(O))=0, if we know the IC of an estimator, then we can use it as an estimating function
 - Estimating equation will be unbiased, up to a second order term

Example: IC of IPTW

- Assume g_0 is known, and strong positivity
- IC of the IPTW estimator:

$$D_{IPTW}(O|g_0, \psi) = \frac{I(A=a)}{g_0(A|W)}Y - \psi$$

- Note: $E_0D_{IPTW}(O|g_0, \psi)=0$

$$\psi_n - \psi = rac{1}{n} \sum_{i=1}^n D(O_i | g_0, \psi)$$
 Exact equality-no remainder term

$$= \frac{1}{n} \sum_{i=1}^{n} \frac{I(A_i = a)}{g_0(A_i|W_i)} Y_i - \psi$$

– For known g_0 , variance of the IPTW estimator well-approximated by var[D(O_i|g₀, ψ_n)]/n

Example: IC of IPTW

- If g_0 is estimated using a correctly specified parametric model, the IC that treats g_0 as known gives conservative variance estimates (overestimates variance)
- Why?
 - IC of IPTW estimator with g_0 estimated=
 IC of IPTW estimator with g_0 known projection
- Estimating g₀ (using a correctly specified parametric model) reduces the variance of the IC and thus of the IPTW estimator

Influence Curves vs. The Efficient Influence Curve

- For a given a statistical estimation problem:
 - n i.i.d. copies of O_i , O^P_0 ∈ M
 - Target parameter $\Psi(P_0)=\psi$
- 1. <u>Influence curves</u> (or influence functions) are estimator- specific
 - Each asymptotically linear estimator has an influence curve
 - Influence curve teaches us about the asymptotic variance of the estimator
- 2. The efficient influence curve is parameter-specific
 - Teaches us about the asymptotic variance of the most efficient regular asymptotically linear estimator for that parameter
 - i.e. the estimator with the lowest asymptotic variance

Efficient Influence Curve

• An estimator is efficient if and only if it is asymptotically linear with influence curve the efficient influence curve $D^*(P_0)$:

$$\hat{\Psi}(P_n) - \Psi(P_0) = \frac{1}{n} \sum_{i=1}^n D^*(P_0)(O_i) + o_P(1/\sqrt{n})$$

- Efficient influence curve needs to be derived for a given estimation problem
- An efficient estimator needs to solve the estimating equation corresponding to efficient influence curve (up to second order term)

$$0 = \frac{1}{n} \sum_{i=1}^{n} D * (P)(O_i)$$

TMLE solves efficient IC equation

• TMLE solves $0 = \frac{1}{n} \sum_{i=1}^{n} D^*(P_n^*)(O_i)$

– Efficient influence curve:

$$D^{*}(P) = \left[\frac{A}{g(A \mid W)} - \frac{1 - A}{g(0 \mid W)}\right] \left[Y - \overline{Q}(A, W)\right] + \overline{Q}(1, W) - \overline{Q}(0, W) - \psi$$
a

- Stage 2 targeting fits ε by maximum likelihood
 - MLE solves score equation $\sum_{i=1}^{n} H_n(A_i, W_i) \Big[Y_i \overline{Q}_n^*(A_i, W_i) \Big] = 0$
 - We defined our parameter-specific H_n and fit with MLE to ensure that empirical mean of a equals 0,
- As a substitution estimator, $\psi_n^{TMLE} = \frac{1}{n} \sum_{i=1}^n \left[\overline{Q}_n^*(1, W_i) \overline{Q}_n^*(0, W_i) \right]$ thus empirical mean of **b** equals 0

Influence curve-based Inference

- Under conditions (see Ch 27 TLB) TMLE is asymptotically linear estimator
- If g_0 and Q_0 are estimated consistently, then the influence curve of the resulting TMLE equals the Efficient Influence Curve

$$D^*(P_0)(O) = \left(\frac{I(A=1)}{g_0(1|W)} - \frac{I(A=0)}{g_0(0|W)}\right) \left(Y - \bar{Q}_0(A,W)\right) + \bar{Q}_0(1|W) - \bar{Q}_0(0,W) - \psi_0$$

- Depends on unknown nuisance parameters g₀ and Q₀
 - Can estimate the influence curve of the TMLE as:

$$IC_n(O) = \left(\frac{I(A=1)}{g_n(1|W)} - \frac{I(A=0)}{g_n(0|W)}\right) \left(Y - \bar{Q}_n^*(A,W)\right) + \bar{Q}_n^*(1|W) - \bar{Q}_n^*(0,W) - \psi_n$$

- If g_0 is estimated consistently (with MLE) but Q_0 is not then this provides conservative approximation of the IC
 - i.e. can use it to get conservative variance estimate

Influence curve-based Inference

- Variance of an asymptotically linear estimator is well-approximated by the variance of its Influence curve/n
- 1. (Conservatively) estimate the TMLE Influence Curve by plugging in estimates of g_n and Q_n
- 2. To estimate variance of the estimator: take sample variance of the estimated influence curve and divide by sample size

• 95% CI:
$$\psi_n(Q_n^*) \pm 1.96 \hat{\sigma}/\sqrt{n}$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n \hat{D}^{*2}(P_n^*)(O_i)$$

Augmented IPTW

- Efficient and double robust
 - Like TMLE: Solves the the estimating equation corresponding to the efficient influence curve
- Defined as a solution to an estimating equation
 - Unlike TMLE: Not a substitution estimator
 - Define estimating function:

$$D^*(O|Q,g,\psi) = \left(\frac{I(A=1)}{g(1|W)} - \frac{I(A=0)}{g(0|W)}\right) \left(Y - \bar{Q}(A,W)\right) + \bar{Q}(1|W) - \bar{Q}(0,W) - \psi$$

- Estimate g and Q and solve estimating equation for ψ

$$0 = \frac{1}{n} \sum_{i=1}^{n} \left[\left(\frac{I(A_i = 1)}{g_n(1|W_i)} - \frac{I(I = 0)}{g_n(0|W_i)} \right) \left(Y_i - \bar{Q}_n(A_{i,i}) \right) + \bar{Q}_n(1|W_i) - \bar{Q}_n(0, W_i) - \psi \right]$$

$$\psi_n = \frac{1}{n} \sum_{i=1}^{n} \left[\left(\frac{I(A_i = 1)}{g_n(1|W_i)} - \frac{I(I = 0)}{g_n(0|W_i)} \right) \left(Y_i - \bar{Q}_n(A_i, i) \right) + \bar{Q}_n(1|W_i) - \bar{Q}_n(0, W_i) \right]$$
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Why we might prefer TMLE to other double robust estimators

- As a substitution estimator, automatically respects the bounds of the model
 - This is important when there are near positivity violations, i.e. g_0 is close to zero
 - Can improve stability
 - Nera positivity violations can still impact the performance of TMLE...
- In general, estimating equations...
 - Might not have a solution
 - Might only have a solution outside parameter space
 - Might have multiple solutions, with no criterion to choose between them...

TMLE: Some take home messages

- TMLE is Double Robust: Consistent if either g_0 or Q_0 are estimated consistently
- TMLE is efficient if g_0 and Q_0 are both estimated consistently at a reasonable rate
- This can translate into real bias and variance improvement
 - Reduce asymptotic bias if initial initial estimator of Q_0 not consistent
 - Reduce finite sample bias
 - Reduce variance

TMLE: Some take home messages

- Use data-adaptive estimation (Super Learning) for g and Q
 - Asymptotic linearity relies on bias disappearing at a fast enough rate
 - Influence curve-based inference relies on g₀ being estimated consistently
 - Conservative variance estimate
 - Good estimation of both g_0 and Q_0 gives us efficiency

TMLE: Beyond simple single time point...

- TMLE is a general method; broad applications
 - Longitudinal problems with time-dependent confounding
 - Parameters of (longitudinal) marginal structural models
 - Dynamic regimes (personalized treatment/adaptive strategies)
 - Informative censoring
 - RCTs (including SMART designs) for improved efficiency
- Estimands, estimators and implementation differ
- R packages implementing all of the above are available (ltmle, tmle, SuperLearner)

Example: Alternative TMLE

- Can also target initial estimate \overline{Q}_n^0 by running an intercept-only weighted logistic regression with:
 - Outcome: Y
 - Offset: $logit(\overline{Q}_n^0)$
 - Weight: $H_n(A, W) = \frac{I(A=1)}{g_n(A \mid W)}$
- i.e. have moved the "clever covariate" to the weights
 - This has benefits in face of positivity violations
 - This is the option implemented in Itmle package

General TMLE Procedure

- 1. Identify the "hardest" parametric submodel to fluctuate initial estimate of P_0
 - Small fluctuation -> maximum change in target
- 2. Identify optimal magnitude of fluctuation by MLE
- Apply optimal fluctuation to Initial estimate to obtain 1st-step TMLE
- 4. Repeat until incremental fluctuation is zero
 - 1-step convergence guaranteed in some important cases
- 5. Final probability distribution solves efficient influence curve equation
 - Basis for asymptotic linearity, normality, and efficiency.
 - Confers double robustness, or, more general, makes bias a second order term.